

Jacob A Tuck

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Visit my portfolio for detailed information on my projects:

<https://tuckja5.wixsite.com/jacob-tuck-portfolio>

Objective: Seeking an internship or co-op experience in the fields of Mechanical Engineering and Engineering Design

Education:	Bachelor of Science, Mechanical Engineering and Engineering Design Rose-Hulman Institute of Technology, Terre Haute, IN Related Courses: Mechatronic Systems, Mechanical Systems, Mechanics of Materials, Materials Engineering, Product Design Studio	May 2027 GPA: 3.76
	Masters of Engineering Management Rose-Hulman Institute of Technology, Terre Haute, IN Related Courses: Risk Analysis & Management, Multi-Objective Optimization, Leadership & Global Challenges, Project Management	May 2027
Skills:	• Proficient in SolidWorks, AutoCAD, Java, Python, MATLAB, C++ • Over 100 hours of machine shop experience, including manual and CNC machinery, welding, and woodworking • Problem-Solving and Conflict Resolution • Rapid Prototyping • Verbal and written professional communication	
Work History:	Willoughby Industries – Indianapolis, IN <i>Engineering Intern</i> • Analyzed manufacturing techniques to design 28 unique fixtures for processing parts • Created parts for the manufacturing fixtures using manual machining techniques • Designed parts and subassemblies for prototyping new products • Assisted in developing a 3D-printing area in the facility for prototyping and showcase models	Summer 2025
Activities:	Rose-Hulman Robotics Team • Workspace Manager for all robotics teams * Elected to oversee the robotics workspace, ensuring it remains a safe and productive space through 5S principles • Combat Robotics member * Design robots for high-intensity applications * Rapid prototyping of parts utilizing 3D-printing * Compare and utilize many materials to balance weight, durability, and stiffness Alpha Phi Omega Service Fraternity – Tau Lambda Chapter • Serve the community via group service events and individual volunteer work • On the service committee where I help organize service events	
Projects:	Mix ‘n Match Rosie – <i>Lovable plush elephant that helps kids learn clothing functions</i> • Communicated effectively with stakeholders to deliver a product that met all the market needs • Applied ASTM standards and testing protocols to ensure the safety of the product SpeedBump – <i>1 lb. combat robot focused on durability</i> • Implemented iterative design to continually test and improve the robot Digi-Die – <i>Physical die that broadcasts roll data to a connected device via Bluetooth</i> • Programmed IoT protocols into the device for wireless use • Packaged electronics into a small form factor using off-the-shelf electrical components • Simulated physical model to maintain a fair roll, and tested the prototype to confirm model Sunflower – <i>Portable solar generator that maximizes efficiency by tracking the sun’s position</i> • Utilized rapid prototyping strategies to design a wiring harness that can be placed in multiple prototype phases with minimal disassembly • Implemented feedback control to reduce the computational complexity * Performed user testing to get design feedback from end-users	

References available upon request